

COS 484

Natural Language Processing

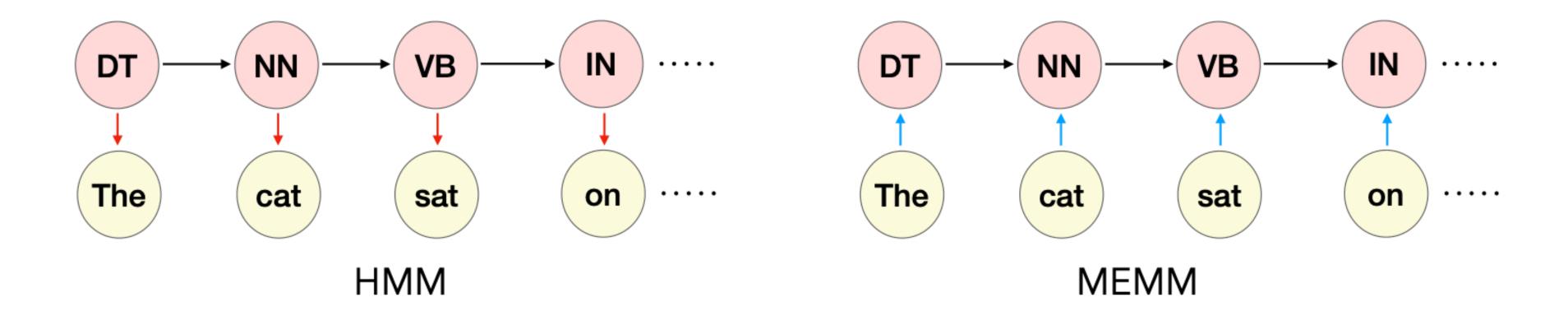
L10: Recurrent Neural Networks

Spring 2022

Announcements

- Midterm Thursday, March 3, 9am to Friday, March 4, 12pm (27 hours)
 - You should aim to open the exam between Thu 9am-Fri 9am (NOT later than that if you want the full 3 hours!!!)
 - This lecture will be included for testing in the midterm
- Open book: you can have access to our course materials (lecture slides, readings, videos) and calculators. Not allowed to access the internet otherwise. You can prepare a cheatsheet **before** the exam if you want.
- Please don't use Ed during the exam period. If you have any questions, please write to cos-484-2022@googlegroups.com (mention the problem ID in your email subject)

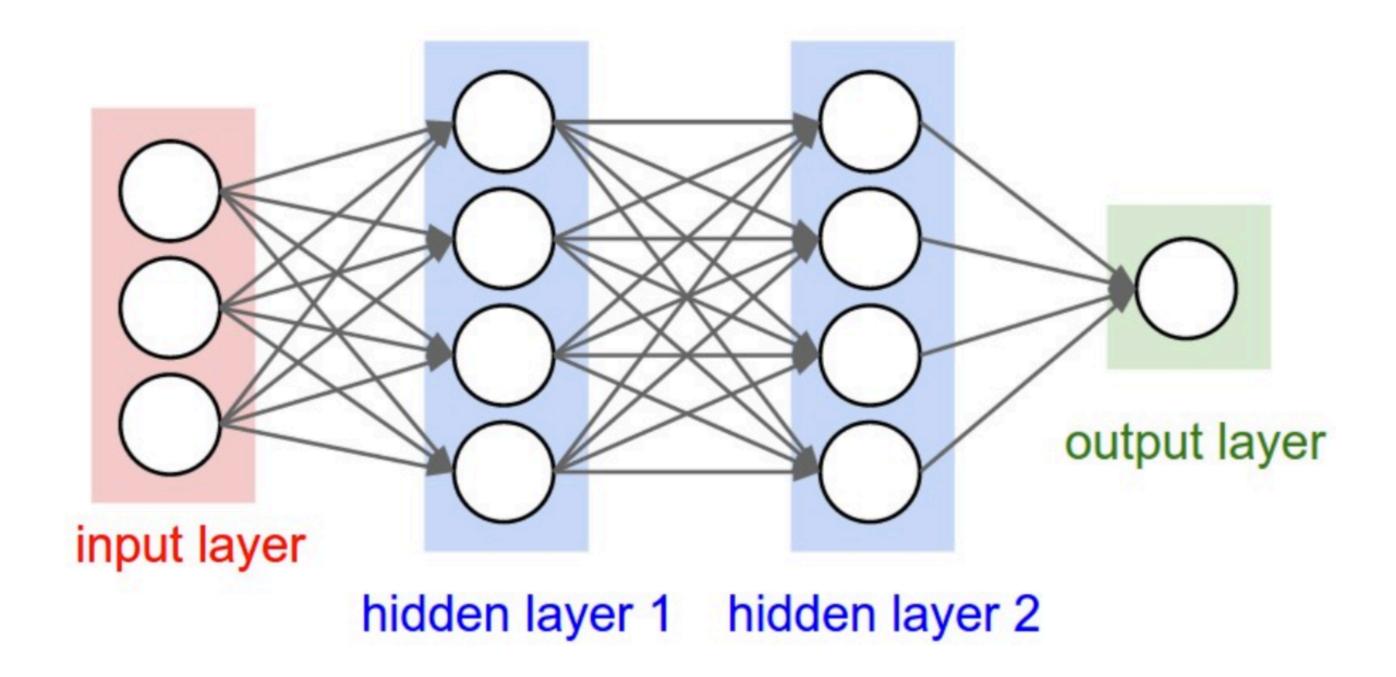
How can we model sequences using neural networks?



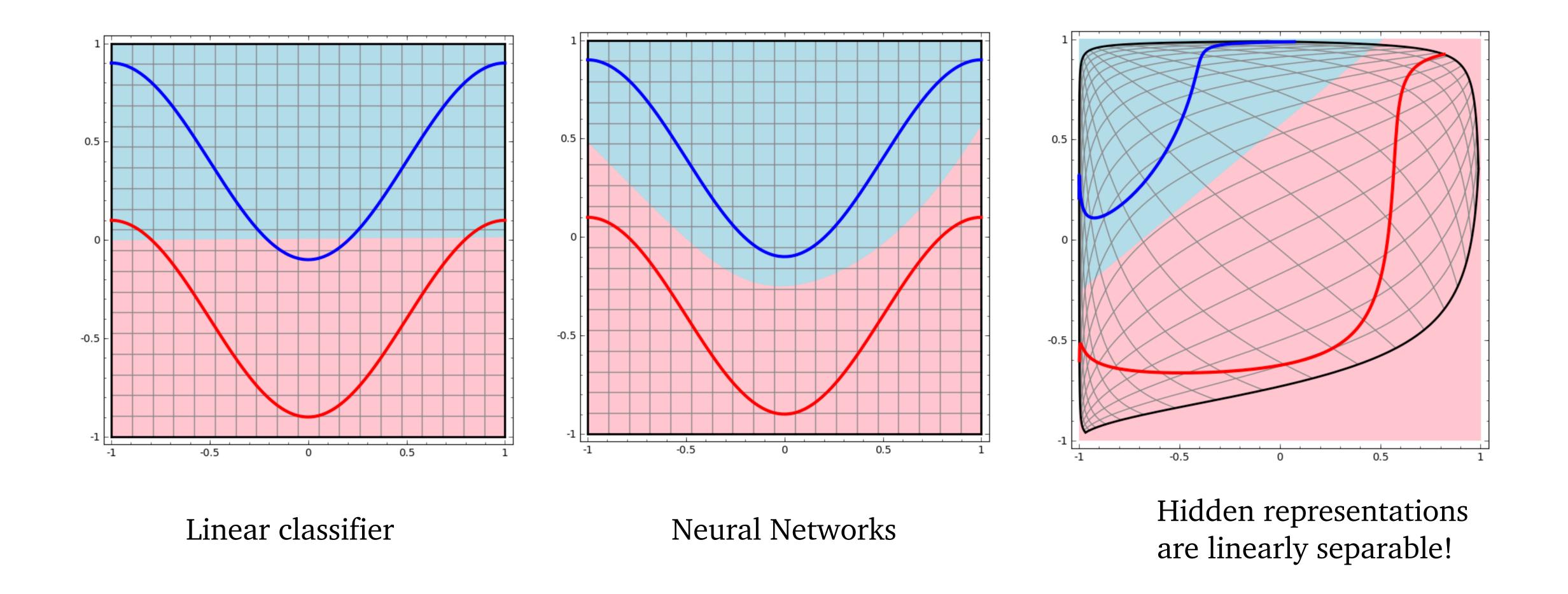
- Recurrent neural networks = A class of neural networks used to model sequences, allowing to handle **variable length inputs**
- Very crucial in NLP problems (different from images) because sentences/paragraphs are variable-length, sequential inputs

Refresher: Feedforward Neural networks

- The neurons are connected to each other, forming a **network**
- The output of a neuron may feed into the inputs of other neurons



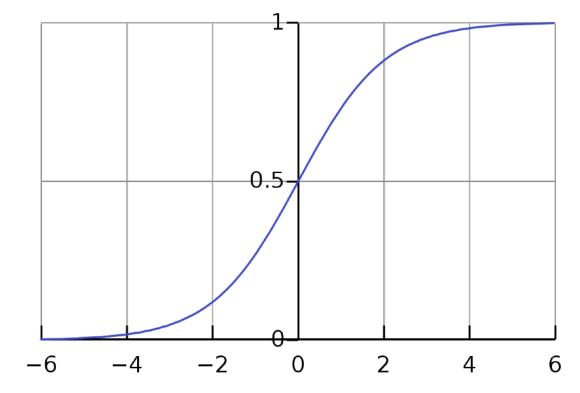
Refresher: Feedforward neural networks



Refresher: Activation functions

sigmoid

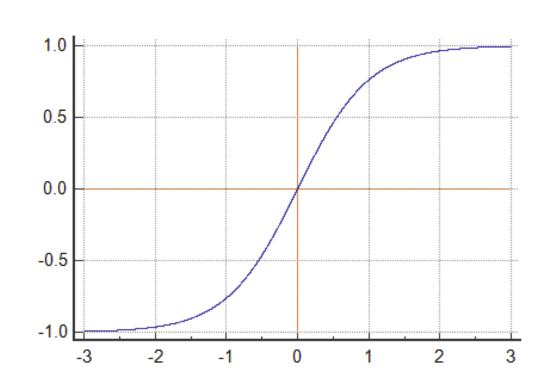
$$f(z) = \frac{1}{1 + e^{-z}}$$



$$f'(z) = f(z) \times (1 - f(z))$$

tanh

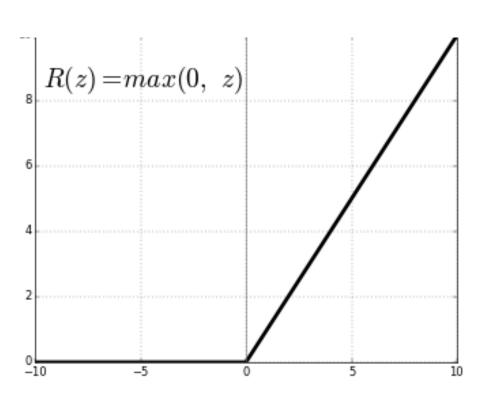
$$f(z) = \frac{e^{2z} - 1}{e^{2z} + 1}$$



$$f'(z) = 1 - f(z)^2$$

ReLU (rectified linear unit)

$$f(z) = \max(0, z)$$



$$f'(z) = \begin{cases} 1 & z > 0 \\ 0 & z < 0 \end{cases}$$

Motivation for RNNs: language models

n-gram language models

Sentence: "the cat sat on the mat"

$$P(\text{the cat sat on the mat}) = P(\text{the}) * P(\text{cat}|\text{the}) * P(\text{sat}|\text{the cat})$$

$$*P(\text{on}|\text{the cat sat}) * P(\text{the}|\text{the cat sat on})$$

$$*P(\text{mat}|\text{the cat sat on the})$$

1st order

 $P(\text{mat}|\text{the cat sat on the}) \approx P(\text{mat}|\text{the})$

2nd order

 $P(\text{mat}|\text{the cat sat on the}) \approx P(\text{mat}|\text{on the})$

kth order Markov

$$P(w_1 w_2 ... w_n) \approx \prod_i P(w_i | w_{i-k} ... w_{i-1})$$

Q: How do we know what size of k is needed?

n-gram language models

the students opened their _____

as the proctor started the clock, the students opened their

Q: Why can't we just keep a very large value of *k*?

Because it is too sparse to estimate the probabilities as *k* increases:

$$P(\boldsymbol{w}|\text{students opened their}) = \frac{\text{count}(\text{students opened their }\boldsymbol{w})}{\text{count}(\text{students opened their})}$$

n-gram language models

Generate text with a 4-gram LM:

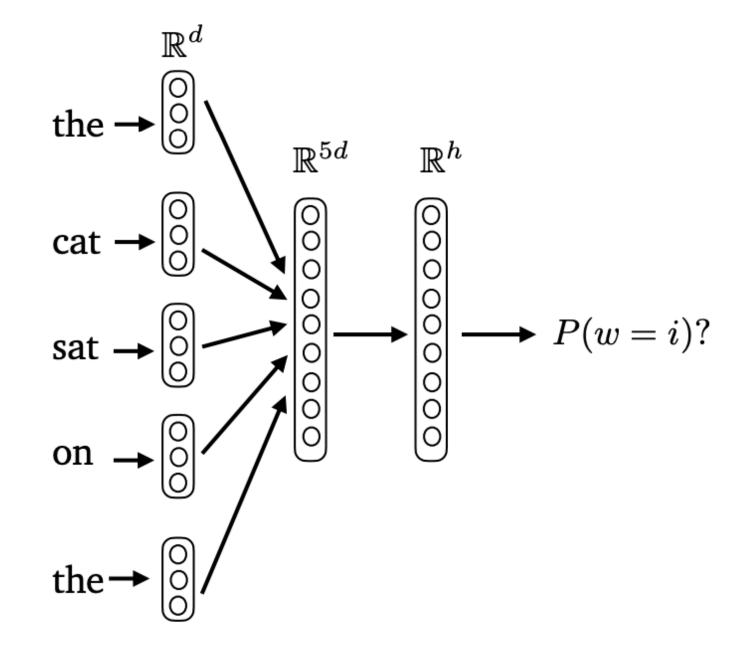
today the price of gold per ton, while production of shoe lasts and shoe industry, the bank intervened just after it considered and rejected an imf demand to rebuild depleted european stocks, sept 30 end primary 76 cts a share.

Surprisingly grammatical!

...but incoherent. We need to consider more than three words at a time if we want to model language well.

Feedforward neural language model

• P(mat | the cat sat on the) = ?



Previous n words = k-th order Markov assumption!

• Input layer (n = 5):

$$\mathbf{x} = [\mathbf{e}_{ ext{the}}; \mathbf{e}_{ ext{cat}}; \mathbf{e}_{ ext{sat}}; \mathbf{e}_{ ext{on}}; \mathbf{e}_{ ext{the}}] \in \mathbb{R}^{dn}$$

Hidden layer

$$\mathbf{h} = \tanh(\mathbf{W}\mathbf{x} + \mathbf{b}) \in \mathbb{R}^h$$

• Output layer (softmax)

$$\mathbf{z} = \mathbf{U}\mathbf{h} \in \mathbb{R}^{|V|}$$
 $P(w=i \mid ext{the cat sat on the})$

$$= \operatorname{softmax}_{i}(\mathbf{z}) = \frac{e^{z_{i}}}{\sum_{k} e^{z_{k}}}$$

Feedforward neural language model

• Input layer (n = 5):

$$\mathbf{x} = [\mathbf{e}_{\mathrm{the}}; \mathbf{e}_{\mathrm{cat}}; \mathbf{e}_{\mathrm{sat}}; \mathbf{e}_{\mathrm{on}}; \mathbf{e}_{\mathrm{the}}] \in \mathbb{R}^{dn}$$

Hidden layer

$$\mathbf{h} = \tanh(\mathbf{W}\mathbf{x} + \mathbf{b}) \in \mathbb{R}^h$$

- $W \in \mathbb{R}^{h \times nd}$ scales with n
- The model learns separate patterns for the same item!

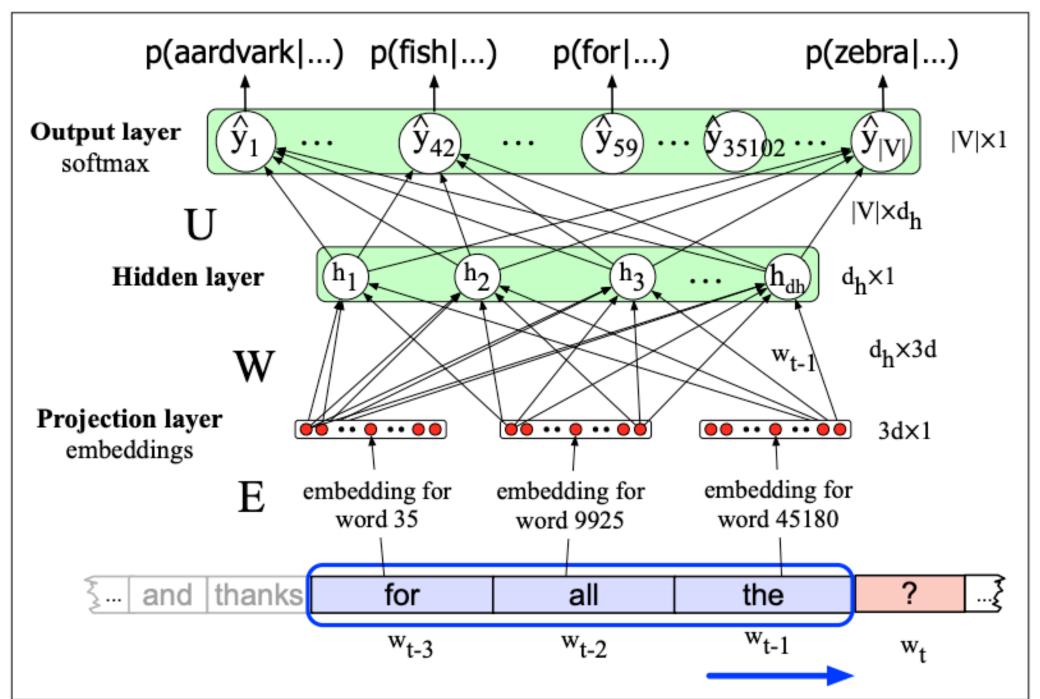
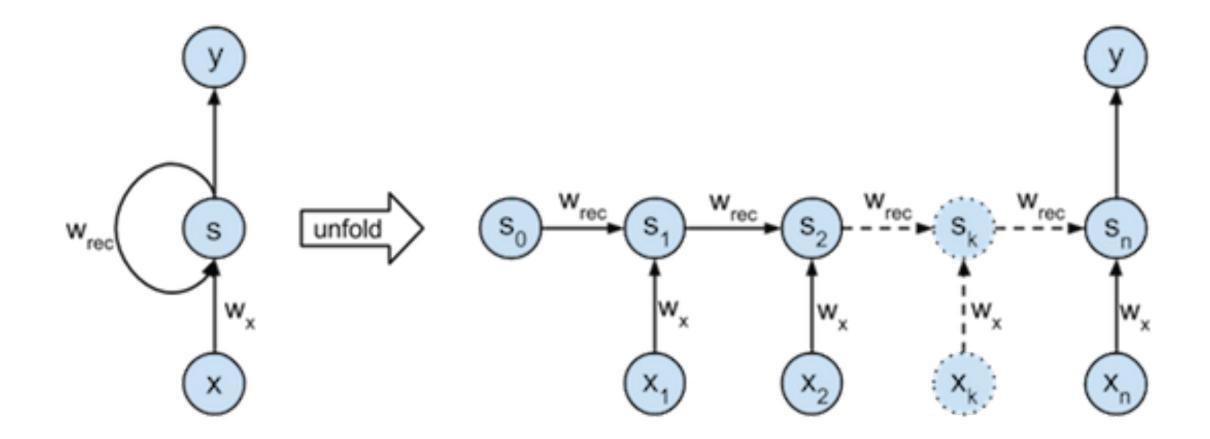


Figure 9.1 A simplified view of a feedforward neural language model moving through a text. At each time step t the network takes the 3 context words, converts each to a d-dimensional embedding, and concatenates the 3 embeddings together to get the $1 \times Nd$ unit input layer x for the network. The output of the network is a probability distribution over the vocabulary representing the models belief with respect to each word being the next possible word.

"all the" appears in different positions of two sliding windows

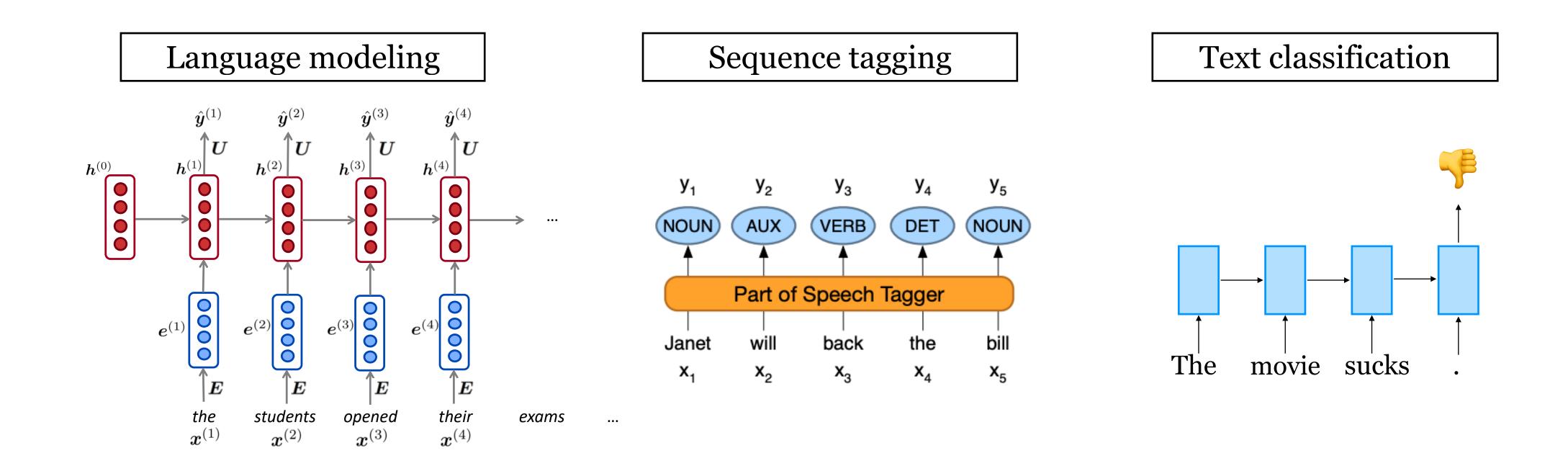
A family of neural networks that can handle variable length inputs



A function: $y = \text{RNN}(\mathbf{x}_1, \mathbf{x}_2, ..., \mathbf{x}_n) \in \mathbb{R}^h$ where $\mathbf{x}_1, ..., \mathbf{x}_n \in \mathbb{R}^d$

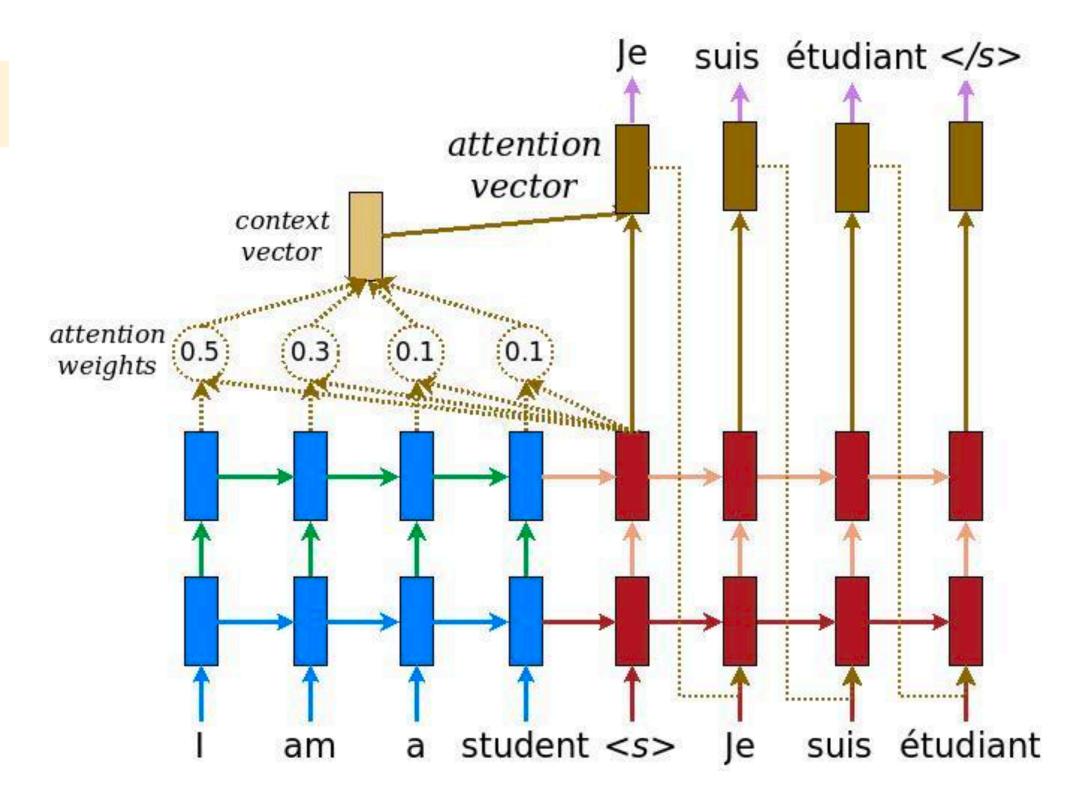
Core idea: apply the same weights repeatedly at different positions

Highly effective approach for language modeling, sequence tagging, text classification:



Form the basis for the modern approaches to machine translation, question answering and dialogue systems:

sequence-to-sequence models



Simple recurrent neural networks

A function: $y = \text{RNN}(\mathbf{x}_1, \mathbf{x}_2, ..., \mathbf{x}_n) \in \mathbb{R}^h$ where $\mathbf{x}_1, ..., \mathbf{x}_n \in \mathbb{R}^d$

 $\mathbf{h}_0 \in \mathbb{R}^h$ is an initial state

$$\mathbf{h}_t = f(\mathbf{h}_{t-1}, \mathbf{x}_t) \in \mathbb{R}^h$$

 \mathbf{h}_t : hidden states which store information from \mathbf{x}_1 to \mathbf{x}_t

Simple RNNs:

$$\mathbf{h}_t = g(\mathbf{W}\mathbf{h}_{t-1} + \mathbf{U}\mathbf{x}_t + \mathbf{b}) \in \mathbb{R}^h$$

g: nonlinearity (e.g. tanh),

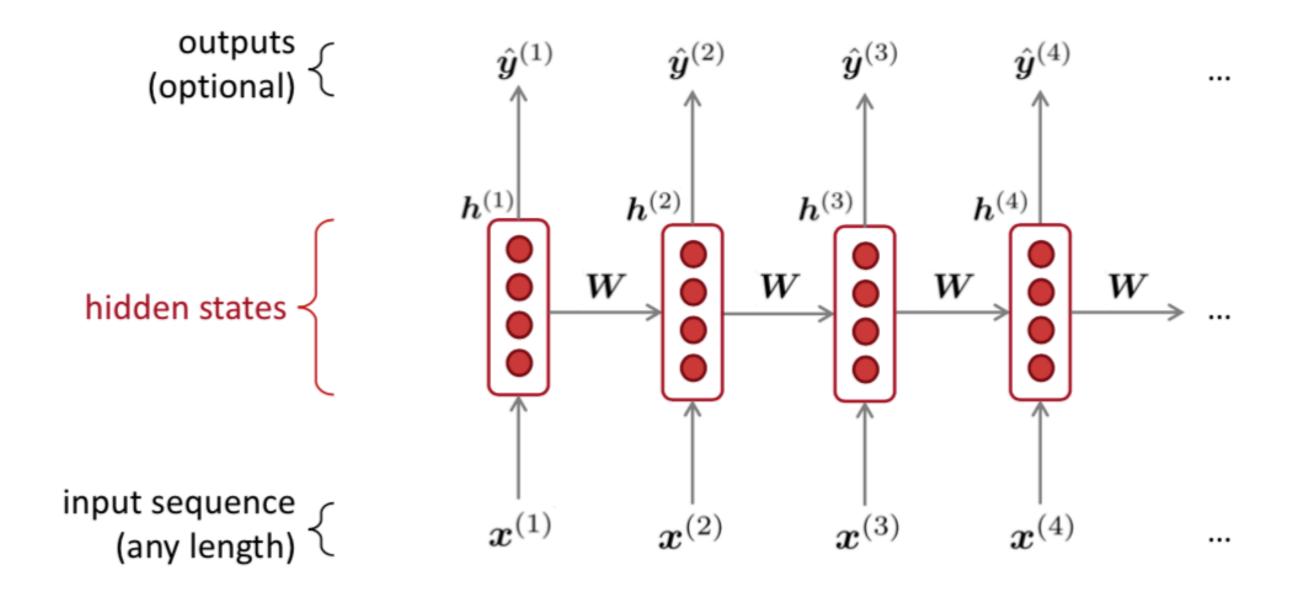
$$\mathbf{W} \in \mathbb{R}^{h \times h}, \mathbf{U} \in \mathbb{R}^{h \times d}, \mathbf{b} \in \mathbb{R}^h$$

This model contains $h \times (h + d + 1)$ parameters, and optionally h for \mathbf{h}_0 (a common way is just to set \mathbf{h}_0 as $\mathbf{0}$)

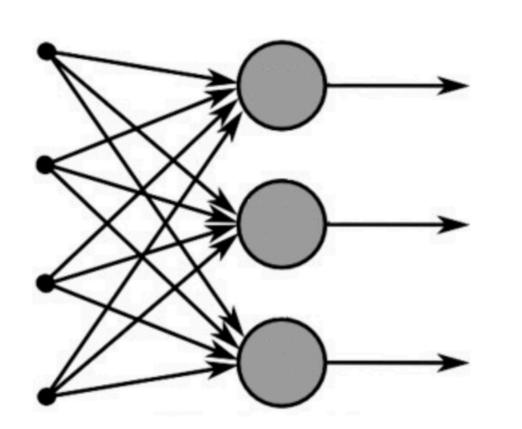
Simple recurrent neural networks

$$\mathbf{h}_t = g(\mathbf{W}\mathbf{h}_{t-1} + \mathbf{U}\mathbf{x}_t + \mathbf{b}) \in \mathbb{R}^h$$

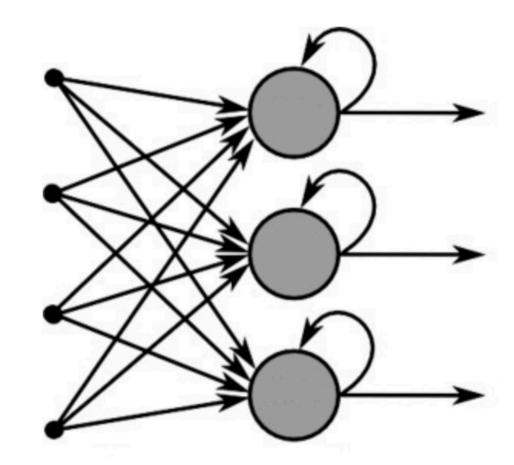
Key idea: apply the same weights W, U, b repeatedly



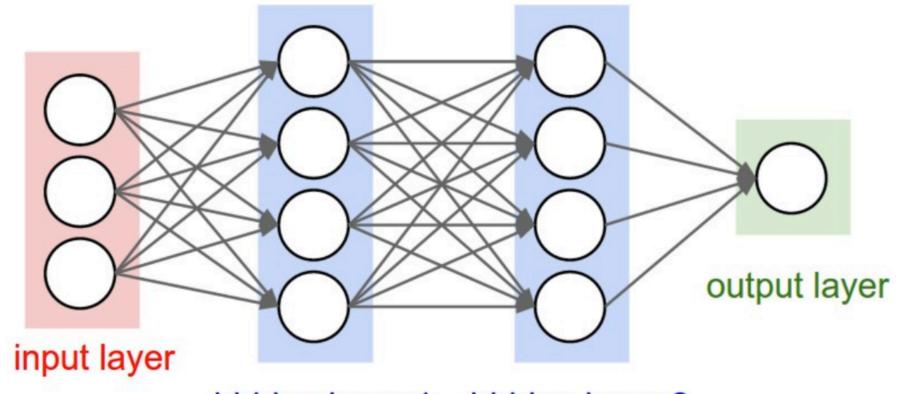
RNNs vs Feedforward NNs



Feed-Forward Neural Network



Recurrent Neural Network



hidden layer 1 hidden layer 2

Recurrent Neural Language Models (RNNLMs)

$$P(w_{1}, w_{2}, ..., w_{n}) = P(w_{1}) \times P(w_{2} \mid w_{1}) \times P(w_{3} \mid w_{1}, w_{2}) \times ... \times P(w_{n} \mid w_{1}, w_{2}, ..., w_{n-1})$$

$$= P(w_{1} \mid \mathbf{h}_{0}) \times P(w_{2} \mid \mathbf{h}_{1}) \times P(w_{3} \mid \mathbf{h}_{2}) \times ... \times P(w_{n} \mid \mathbf{h}_{n-1}) \qquad \text{No Markov assumption here!}$$

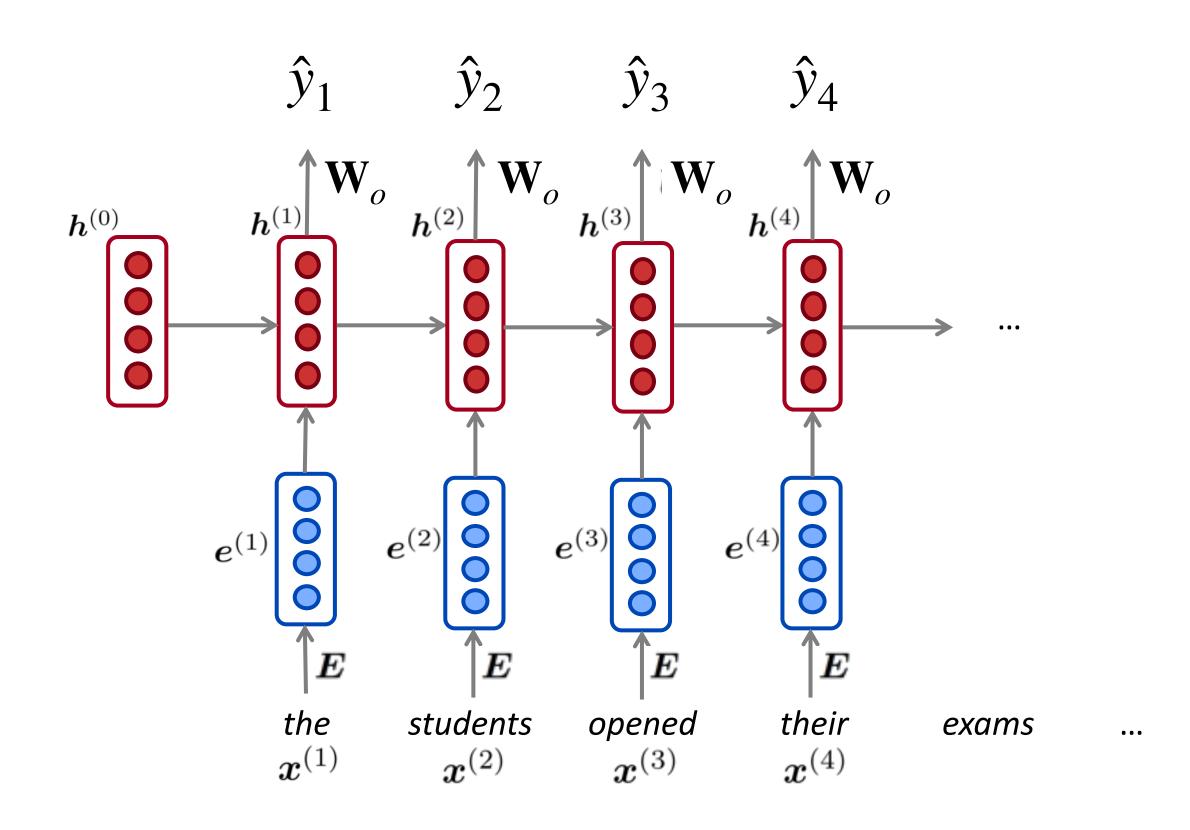
$$= \hat{y}_{0}(w_{1}) \times \hat{y}_{1}(w_{2}) ... \times \hat{y}_{n-1}(w_{n})$$

output weight matrix

- Denote $\hat{\mathbf{y}}_t = softmax(\mathbf{W}_o \mathbf{h}_t)$, $\mathbf{W}_o \in \mathbb{R}^{|V| \times h}$
- Cross-entropy loss:

$$L(\theta) = -\frac{1}{n} \sum_{t=1}^{n} \log \hat{\mathbf{y}}_{t-1}(w_t)$$

$$\theta = \{\mathbf{W}, \mathbf{U}, \mathbf{b}, \mathbf{W}_o, \mathbf{E}\}$$



Progress on language models

On the Penn Treebank (PTB) dataset

Metric: perplexity

KN5: Kneser-Ney 5-gram

Model	Individual		
KN5	141.2		
KN5 + cache	125.7		
Feedforward NNLM	140.2		
Log-bilinear NNLM	144.5		
Syntactical NNLM	131.3		
Recurrent NNLM	124.7		
RNN-LDA LM	113.7		

Progress on language models

On the Penn Treebank (PTB) dataset

Metric: perplexity

Model	#Param	Validation	Test
Mikolov & Zweig (2012) – RNN-LDA + KN-5 + cache	9M [‡]	-	92.0
Zaremba et al. (2014) – LSTM	20M	86.2	82.7
Gal & Ghahramani (2016) - Variational LSTM (MC)	20M	-	78.6
Kim et al. (2016) - CharCNN	19M	-	78.9
Merity et al. (2016) - Pointer Sentinel-LSTM	21M	72.4	70.9
Grave et al. (2016) – LSTM + continuous cache pointer [†]	-	-	72.1
Inan et al. (2016) - Tied Variational LSTM + augmented loss	24M	75.7	73.2
Zilly et al. (2016) – Variational RHN	23M	67.9	65.4
Zoph & Le (2016) – NAS Cell	25M	-	64.0
Melis et al. (2017) – 2-layer skip connection LSTM	24M	60.9	58.3
Merity et al. (2017) - AWD-LSTM w/o finetune	24M	60.7	58.8
Merity et al. (2017) – AWD-LSTM	24M	60.0	57.3
Ours – AWD-LSTM-MoS w/o finetune	22M	58.08	55.97
Ours – AWD-LSTM-MoS	22M	56.54	54.44
Merity et al. (2017) – AWD-LSTM + continuous cache pointer [†]	24M	53.9	52.8
Krause et al. (2017) – AWD-LSTM + dynamic evaluation [†]	24M	51.6	51.1
Ours – AWD-LSTM-MoS + dynamic evaluation [†]	22M	48.33	47.69

We will talk about LSTMs later

RNNs: pros and cons

Advantages:

- Can process any length input
- Computation for step t can (in theory) use information from many steps back
- Model size doesn't increase for longer input context

Disadvantages:

- Recurrent computation is slow (can't parallelize) Transformer networks can!
- In practice, difficult to access information from many steps back (optimization issue) We will see some advanced RNNs (e.g., LSTMs, GRUs)

Training RNNLMs

- Forward pass + backward pass (compute gradients)
- Forward pass:

$$L = 0 \quad \mathbf{h}_0 = \mathbf{0}$$
For $t = 1, 2, ..., n$

$$y = -\log \operatorname{softmax}(\mathbf{W}_o \mathbf{h}_{t-1})(w_t)$$

$$\mathbf{x}_t = e(w_t)$$

$$\mathbf{h}_t = g(\mathbf{W} \mathbf{h}_{t-1} + \mathbf{U} \mathbf{x}_t + \mathbf{b})$$

$$L = L + \frac{1}{n}y$$

Zoom poll



What is the running time of a forward pass?

(a)
$$O(h \times (d + h + |V|))$$

(b)
$$O(n \times h \times (d + h + |V|))$$

(c)
$$O(n \times (d + h + |V|))$$

(d)
$$O(n \times h \times (d+h))$$

The answer is (b).

$$L = 0 \quad \mathbf{h}_0 = \mathbf{0}$$
For $t = 1, 2, ..., n$

$$y = -\log \operatorname{softmax}(\mathbf{W}_o \mathbf{h}_{t-1})(w_t)$$

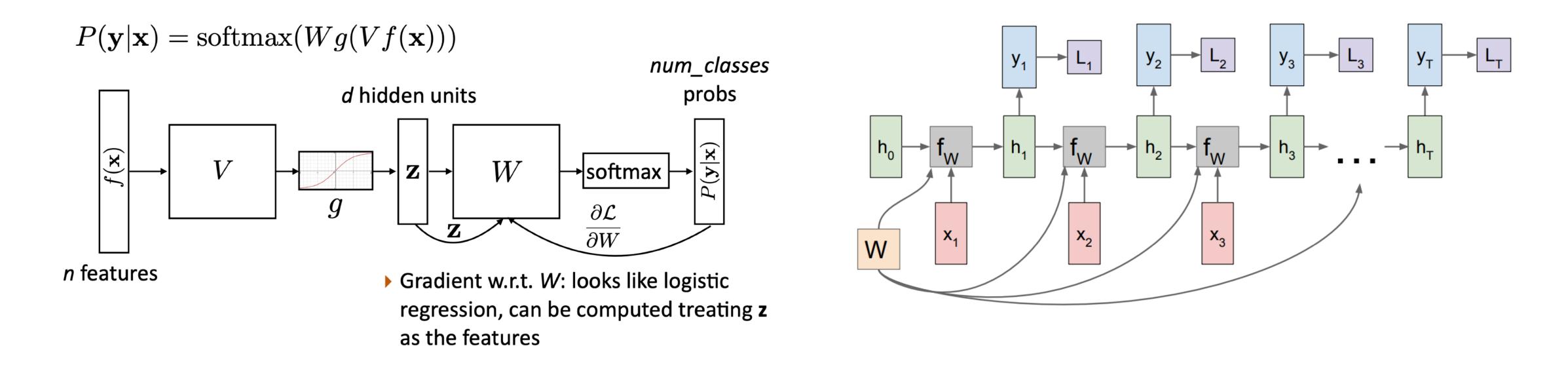
$$\mathbf{x}_t = e(w_t)$$

$$\mathbf{h}_t = g(\mathbf{W} \mathbf{h}_{t-1} + \mathbf{U} \mathbf{x}_t + \mathbf{b})$$

$$L = L + \frac{1}{2}y$$

Training RNNLMs

- Backward pass:
 - Backpropagation? Yes, but not that simple!



• The algorithm is called Backpropagation Through Time (BPTT).

Backpropagation through time

$$\mathbf{h}_1 = g(\mathbf{W}\mathbf{h}_0 + \mathbf{U}\mathbf{x}_1 + \mathbf{b})$$

$$\mathbf{h}_2 = g(\mathbf{W}\mathbf{h}_1 + \mathbf{U}\mathbf{x}_2 + \mathbf{b})$$

$$\mathbf{h}_3 = g(\mathbf{W}\mathbf{h}_2 + \mathbf{U}\mathbf{x}_3 + \mathbf{b})$$

$$L_3 = -\log \hat{\mathbf{y}}_3(w_4)$$

First, compute gradient with respect to hidden vector of last time step: $\frac{\partial L_3}{\partial \mathbf{h}_3}$

$$\frac{\partial L_3}{\partial \mathbf{W}} = \frac{\partial L_3}{\partial \mathbf{h}_3} \frac{\partial \mathbf{h}_3}{\partial \mathbf{W}} + \frac{\partial L_3}{\partial \mathbf{h}_3} \frac{\partial \mathbf{h}_3}{\partial \mathbf{h}_2} \frac{\partial \mathbf{h}_2}{\partial \mathbf{W}} + \frac{\partial L_3}{\partial \mathbf{h}_3} \frac{\partial \mathbf{h}_3}{\partial \mathbf{h}_2} \frac{\partial \mathbf{h}_3}{\partial \mathbf{h}_1} \frac{\partial \mathbf{h}_3}{\partial \mathbf{W}}$$

More generally,
$$\frac{\partial L}{\partial \mathbf{W}} = -\frac{1}{n} \sum_{t=1}^{n} \sum_{k=1}^{t} \frac{\partial L_t}{\partial \mathbf{h}_t} \left(\prod_{j=k+1}^{t} \frac{\partial \mathbf{h}_j}{\partial \mathbf{h}_{j-1}} \right) \frac{\partial \mathbf{h}_k}{\partial \mathbf{W}}$$

If *k* and *t* are far away, the gradients can grow/shrink exponentially (called the gradient exploding or gradient vanishing problem)

Zoom poll



What will happen if the gradients become too large or too small?

- (a) If too large, the model will become difficult to converge
- (b) If too small, the model can't capture long-term dependencies
- (c) If too small, the model may capture a wrong recent dependency
- (d) All of the above

All of these are correct, so (d) ©

Backpropagation through time

One solution for gradient exploding is called **gradient clipping** — if the norm of the gradient is greater than some threshold, scale it down before applying SGD update.

Algorithm 1 Pseudo-code for norm clipping
$$\hat{\mathbf{g}} \leftarrow \frac{\partial \mathcal{E}}{\partial \theta}$$

$$\mathbf{if} \quad ||\hat{\mathbf{g}}|| \geq threshold \ \mathbf{then}$$

$$\hat{\mathbf{g}} \leftarrow \frac{threshold}{||\hat{\mathbf{g}}||} \hat{\mathbf{g}}$$

$$\mathbf{end} \quad \mathbf{if}$$

Backpropagation through time

Gradient vanishing is a harder problem to solve:

When she tried to print her tickets, she found that the printer was out of toner. She went to the stationery store to buy more toner. It was very overpriced. After installing the toner into the printer, she finally printed her _____

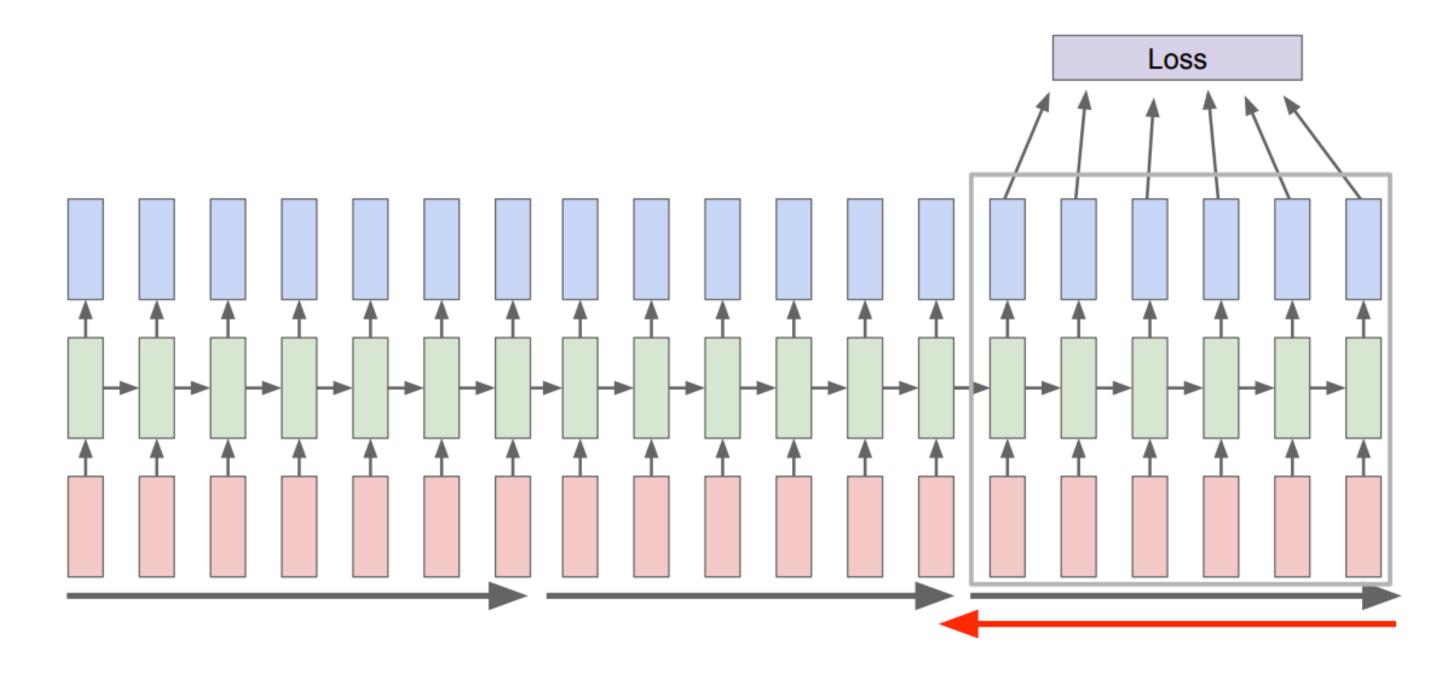
The writer of the books is/are (planning a sequel)

Syntactic recency: The <u>writer</u> of the books <u>is</u> (correct)

Sequential recency: The writer of the books are (incorrect)

Truncated backpropagation through time

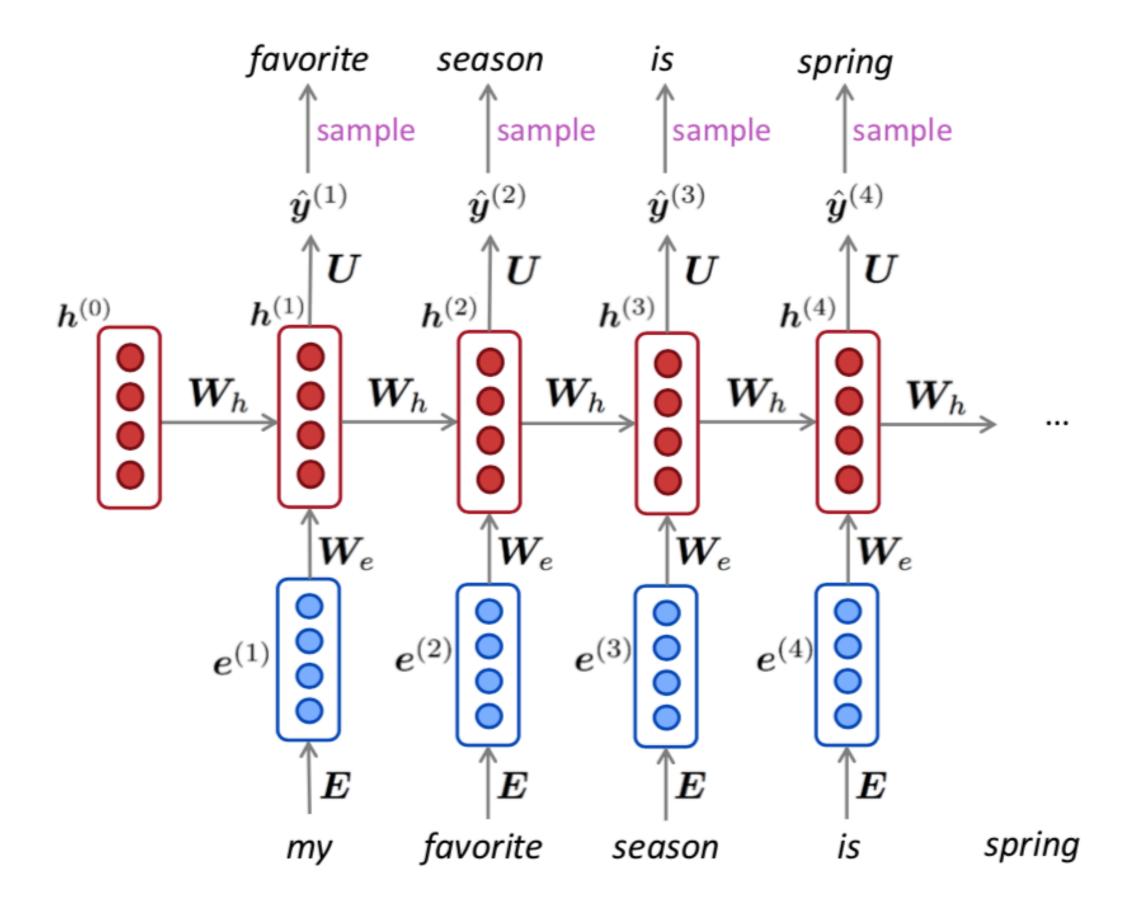
Backpropagation is very expensive if you handle long sequences



- Run forward and backward through chunks of the sequence instead of whole sequence
- Carry hidden states forward in time forever, but only back-propagate for some smaller number of steps

Applications and Variants

Application: Text Generation



You can generate text by **repeated sampling.**Sampled output is next step's input.

You can train an RNN-LM on any kind of text, then generate text in that style.

Good afternoon. God bless you.

The United States will step up to the cost of a new challenges of the American people that will share the fact that we created the problem. They were attacked and so that they have to say that all the task of the final days of war that I will not be able to get this done. The promise of the men and women who were still going to take out the fact that the American people have fought to make sure that they have to be able to protect our part. It was a chance to stand together to completely look for the commitment to borrow from the American people. And the fact is the men and women in uniform and the millions of our country with the law system that we should be a strong stretcks of the forces that we can afford to increase our spirit of the American people and the leadership of our country who are on the Internet of American lives.

Thank you very much. God bless you, and God bless the United States of America.



You can train an RNN-LM on any kind of text, then generate text in that style.

"Sorry," Harry shouted, panicking — "I'll leave those brooms in London, are they?"

"No idea," said Nearly Headless Nick, casting low close by Cedric, carrying the last bit of treacle Charms, from Harry's shoulder, and to answer him the common room perched upon it, four arms held a shining knob from when the spider hadn't felt it seemed. He reached the teams too.

"You believe if we've got friendly to come down and out of the library. I think I've found out Potter, I asked you he had . . . me. I think he's not telling Dobby if yeh get with our Hogwarts ..."



Let's have some fun

You can train an RNN-LM on any kind of text, then generate text in that style.

```
\begin{proof}
We may assume that $\mathcal{I}$ is an abelian sheaf on $\mathcal{C}$.
\item Given a morphism $\Delta : \mathcal{F} \to \mathcal{I}$
is an injective and let $\mathfrak q$ be an abelian sheaf on $X$.
Let $\mathcal{F}$ be a fibered complex. Let $\mathcal{F}$ be a category.
\begin{enumerate}
\item \hyperref[setain-construction-phantom]{Lemma}
\label{lemma-characterize-quasi-finite}

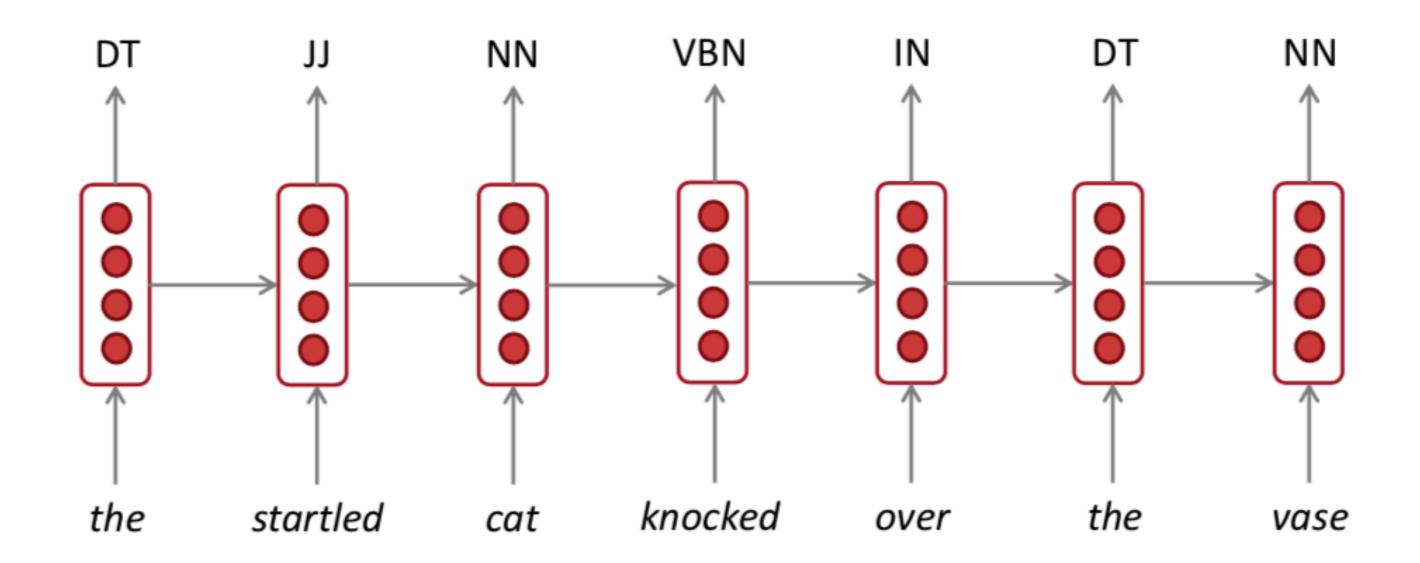
Let $\mathcal{F}$ be an abelian quasi-coherent sheaf on $\mathcal{C}$$.

Let $\mathcal{F}$ be a coherent $\mathcal{O}_X$-module. Then
$\mathcal{F}$ is an abelian catenary over $\mathcal{C}$$.
\item The following are equivalent
\begin{enumerate}
\item $\mathcal{F}$ is an $\mathcal{O}_X$-module.
\end{lemma}
\end{\lemma}
```

Application: Sequence Tagging

Input: a sentence of *n* words: $x_1, ..., x_n$

Output: $y_1, ..., y_n, y_i \in \{1, ..., C\}$



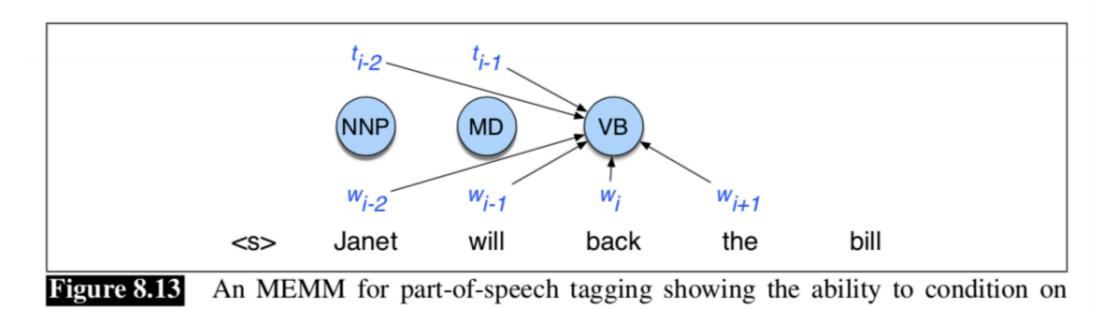
$$P(y_i = k) = softmax_k(\mathbf{W}_o \mathbf{h}_i) \qquad \mathbf{W}_o \in \mathbb{R}^{C \times h} \qquad L = -\frac{1}{n} \sum_{i=1}^n \log P(y_i = k)$$

Application: Sequence Tagging

Input: a sentence of *n* words: $x_1, ..., x_n$

Output: $y_1, ..., y_n, y_i \in \{1, ..., C\}$

The model doesn't model dependencies between output labels!



[advanced]

more features.

• We can still model the joint probabilities over $\{y_1, y_2, ..., y_n\}$ and use beam search at decoding time

the

startled

knocked

cat

over

NN

vase

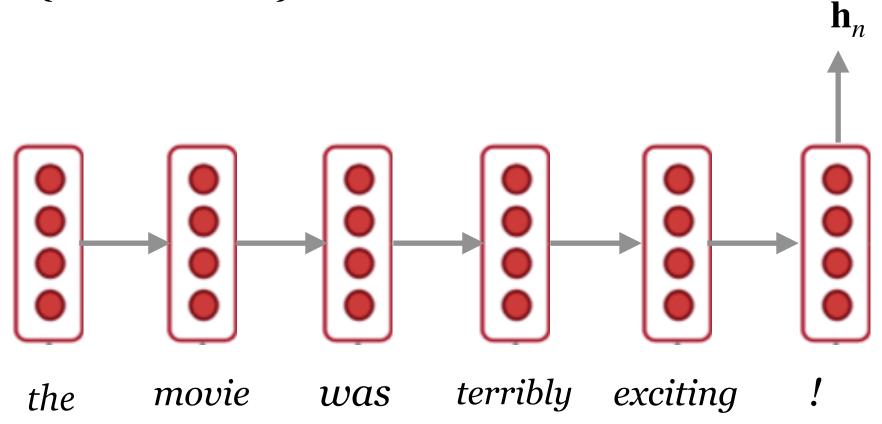
• The main difference compared to MEMMs - you don't need to define manual features and the RNNs can derive features automatically!

(Lample et al, 2016): Neural Architectures for Named Entity Recognition

Application: Text Classification

Input: a sentence of *n* words

Output: $y \in \{1, 2, ..., C\}$



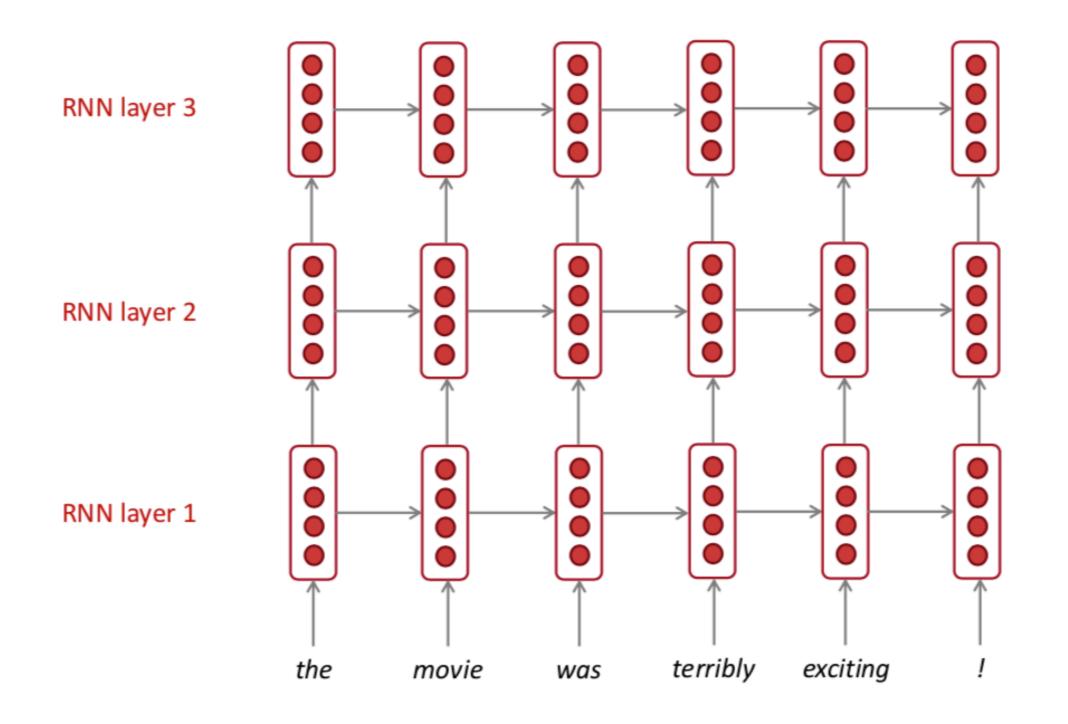
$$P(y = k) = softmax_k(\mathbf{W}_o \mathbf{h}_n) \qquad \mathbf{W}_o \in \mathbb{R}^{C \times h}$$

$$L = -\log P(y = c)$$

Multi-layer RNNs

- RNNs are already "deep" on one dimension (unroll over time steps)
- We can also make them "deep" in another dimension by applying multiple RNNs
- Multi-layer RNNs are also called stacked RNNs.

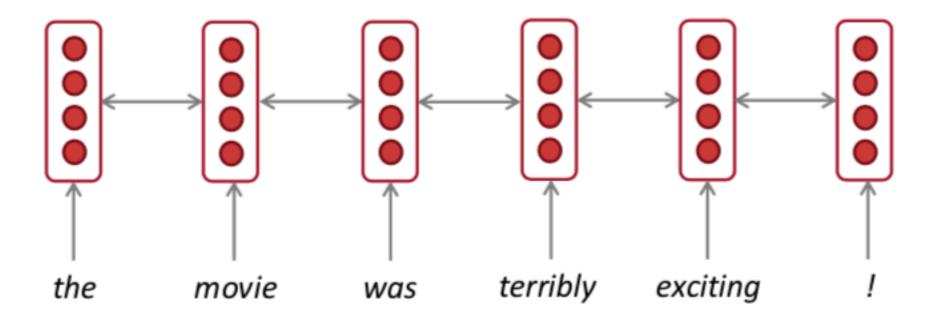
Multi-layer RNNs



The hidden states from RNN layer i are the inputs to RNN layer i+1

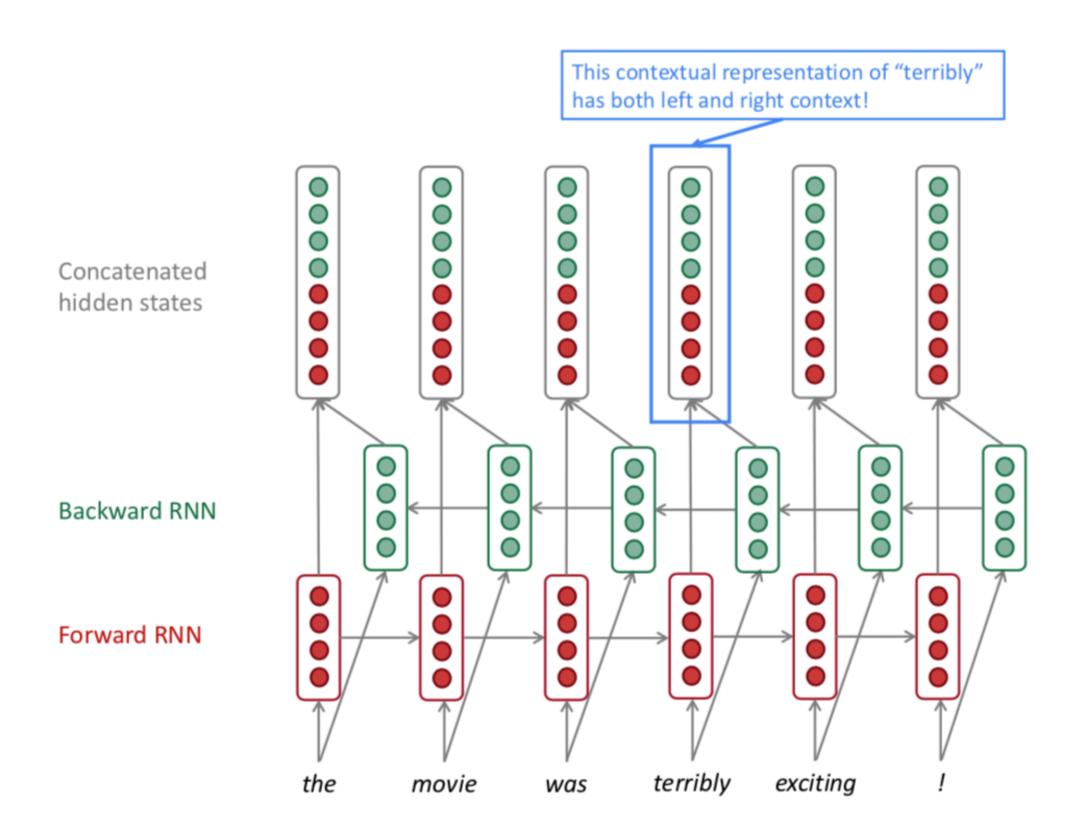
- In practice, using 2 to 4 layers is common (usually better than 1 layer)
- Transformer networks can be up to 24 layers with lots of skip-connections.

• Bidirectionality is important in language representations:



terribly:

- left context "the movie was"
- right context "exciting!"



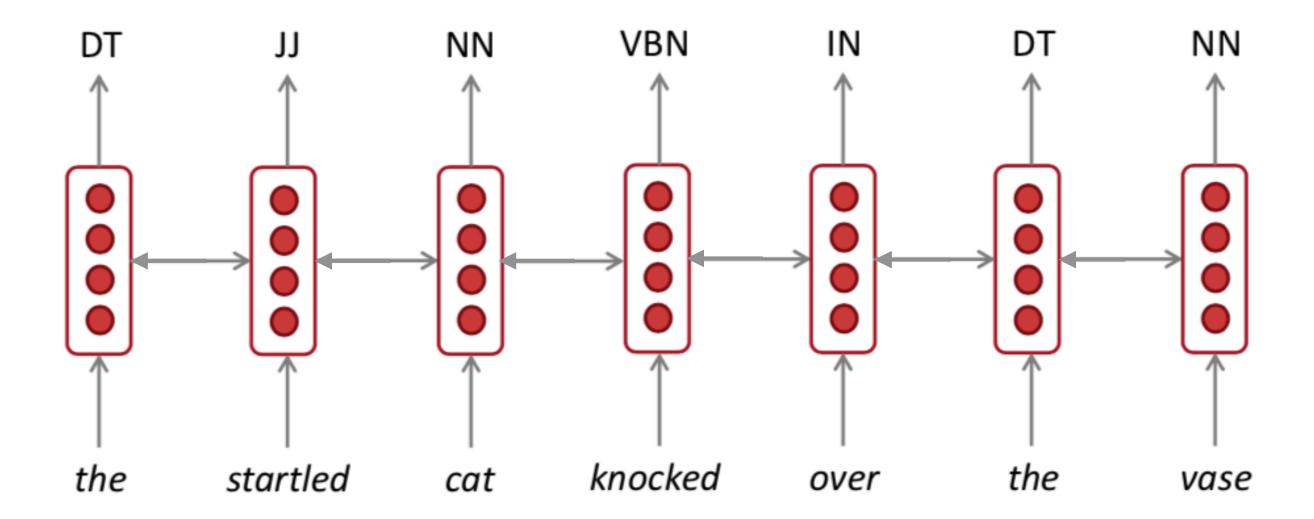
$$\mathbf{h}_t = f(\mathbf{h}_{t-1}, \mathbf{x}_t) \in \mathbb{R}^h$$

$$\overrightarrow{\mathbf{h}}_{t} = f_{1}(\overrightarrow{\mathbf{h}}_{t-1}, \mathbf{x}_{t}), t = 1, 2, \dots n$$

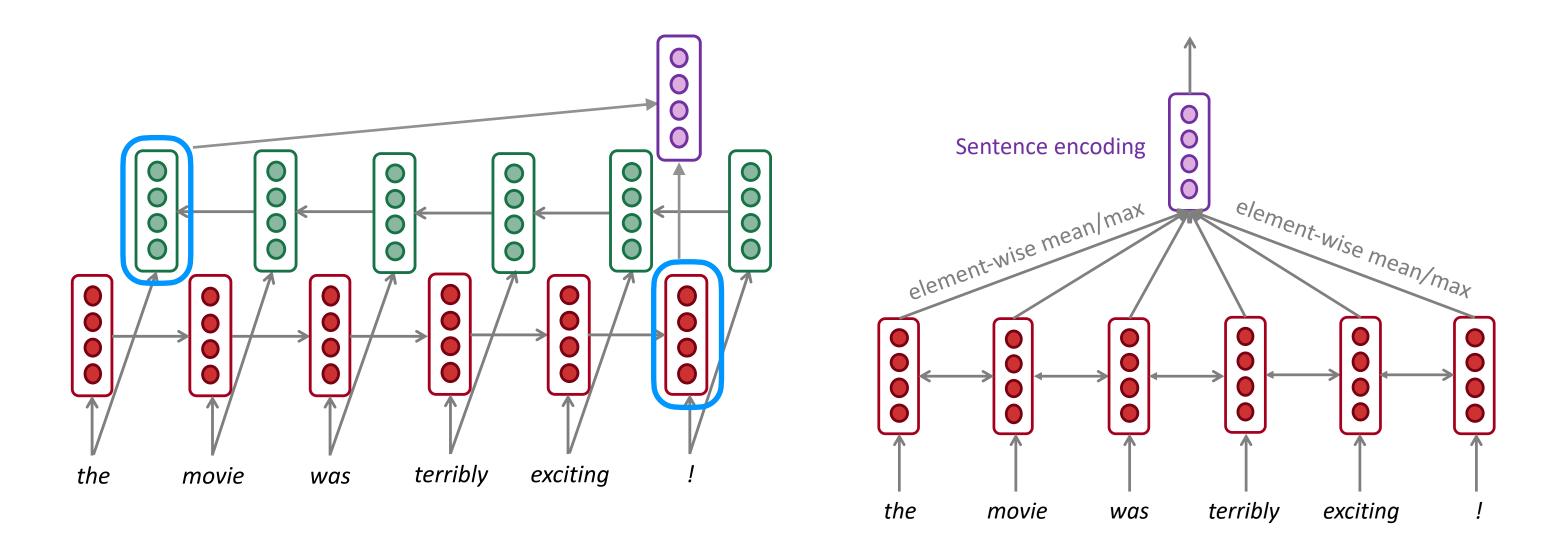
$$\overleftarrow{\mathbf{h}}_{t} = f_{2}(\overleftarrow{\mathbf{h}}_{t+1}, \mathbf{x}_{t}), t = n, n - 1, \dots 1$$

$$\overleftarrow{\mathbf{h}}_{t} = [\overleftarrow{\mathbf{h}}_{t}, \overrightarrow{\mathbf{h}}_{t}] \in \mathbb{R}^{2h}$$

• Sequence tagging: Yes! (esp. important)



- Sequence tagging: Yes!
- Text classification: Yes!
 - Common practice: concatenate the last hidden vectors in two directions or take the mean/max over all the hidden vectors



• Text generation: No. Because we can't see the future to predict the next word.

A note on terminology

• Simple RNNs are also called vanilla RNNs



• Sometimes vanilla RNNs don't work that well, so we need to use some advanced

RNN variants such as LSTMs



or GRUs



(next lecture)

• In practice, we generally use multi-layer RNNs





... together with fancy ingredients such as residual connections with self-attention, variational dropout..

Good luck with the midterm!